Course Syllabus	EECS 4200 – Feedback Control Systems
Credits/Contact Hours	3 credit hours & three 50-minute lecture contact hours per week.
Instructor's Name	Dr. Richard G. Molyet
Textbook	R.C. Dorf and R.H. Bishop, "Modern Control Systems," Pearson Prentice Hall, 13 <sup>th</sup> edition, 2017.
Course Information	Feedback methods for the control of dynamic systems. Topics include: modeling, characteristics and performance of feedback systems, stability, root locus and frequency response methods and computer simulation.
	Derwined for EE major
Specific Goals-Student Learning Objectives (SLOs)	<ul> <li>The student will be able to</li> <li>1. Formulate mathematical models for linear, time-invariant electrical, mechanical and electromechanical systems.</li> <li>2. Construct block diagram and signal flow graph representations of linear, time-invariant systems.</li> <li>3. Reduce block diagram and signal flow graph representations to a single transfer function.</li> <li>4. Determine applications of closed loop systems.</li> <li>5. Analyze and design control system specifications in the time domain.</li> <li>6. Determine the stability of control systems.</li> <li>7. Determine the relation between characteristic equation root location and control system performance.</li> <li>8. Analyze the frequency response characteristics of a control system.</li> <li>9. Apply feedback control techniques to contemporary automatic control systems.</li> <li>10. Use MATLAB and Simulink to analyze open and closed loop control systems.</li> </ul>
Topics	<ol> <li>Introduction to control systems</li> <li>Mathematical models</li> <li>Block diagrams/signal flow graphs</li> <li>State variable representation</li> <li>Feedback system characteristics</li> <li>Performance of feedback systems</li> <li>Stability of linear feedback systems</li> <li>Root locus method</li> <li>Frequency response methods</li> </ol>