Course Syllabus EECS 4220 – Programmable Logic Controllers

Credits & Contact hours 3 credit hours & two 75-minute lecture contact hours.

Coordinator Dr. William T. Evans

Textbook Free online text at www.eng.utoledo.edu/~wevans

Course Information An introduction to programmable logic controllers (PLCs), process

control algorithms, interfacing of sensors and other I/O devices,

simulation and networking.

Prerequisite: EECS 3210

Elective course

Specific Goals- Students Learning Objectives The student will be able to

1. Demonstrate knowledge of programmable logic controllers.

- 2. Demonstrate knowledge of process control systems.
- 3. Program using ladder logic programming of software.
- 4. Design PLC based system for process control.
- 5. Use digital and analog I/O.
- 6. Understand various timers, counters, fault and interrupt systems.
- 7. Define and design a PLC based process control system, its software/hardware design.
- 8. Write a report and present results.

Topics

- 1. Introduction to Programmable Logic Controllers (PLCs) and its architecture.
- 2. Input/output modules, power supplies, opto isolation and memory map
- 3. Allen-Bradley Compact Logix Instruction Set
- 4. Siemens Instruction Set
- 5. Addressing considerations for both PLC processors
- 6. IEC 61131-3 programming language standard
- 7. Ladder logic programming including combinational logic, branching and other rung conditions
- 8. Start/stop circuits, special contacts, transitional contacts, latching instructions, memory circuit constructs and S/R to Seal Circuit transfer
- 9. Timers, timing diagrams and examples for timer applications
- 10. Counter basic programming, Arithmetic, program control instructions

- 11. Control Panel Construction Standards
- 12. Control standards external to the Control Panel
- 13. Analog module-programming examples, Fault and interrupt service routines
- 14. Sequential Programming Concepts
- 15. Process control PLC programming including Faceplate
- 16. HMI Programming Organization
- 17. Siemens Function/Function Blocks
- 18. Motion Control of single axis motion systems