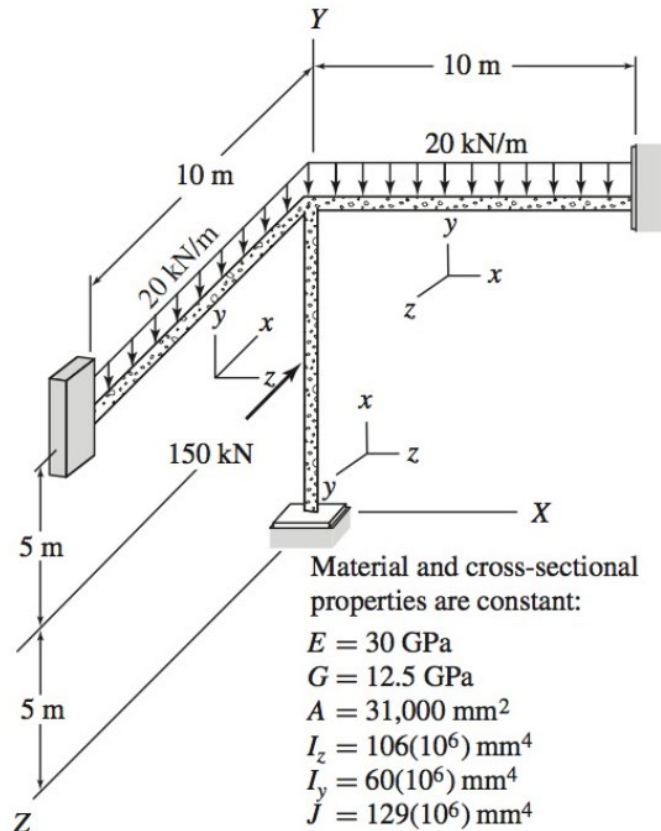


Determine the joint displacements, member local end forces, and support reactions for the space frames shown, using the matrix stiffness method. Use **SAP2000** only.



Your submission must include the followings:

- A joint displacements vector (i.e., a single column) which will list the displacements with the following order: X, Y, and Z displacements (in m using six decimal numbers), and X, Y, and Z rotations (in rad using six decimal numbers) for each node (i.e., six values per node). Use positive values for the positive global coordinate system directions.
- A member local end forces vector (i.e., a single column) which will list the forces with the following order: x, y, and z forces (in kN using three decimal numbers), and x, y, and z moments (in kNm using three decimal numbers) for each node (i.e., twelve values per member). Use positive values for the positive local coordinate system directions.
- A support reaction vector (i.e., a single column) which will list the reactions with the following order: X, Y, and Z forces (in kN using three decimal numbers), and X, Y, and Z moments (in kNm using three decimal numbers) for each node (i.e., six values per node). Use positive values for the positive global coordinate system directions.
- Print the axial force, shear force and moment diagrams with peak values shown on the diagrams. Plot positive values above the horizontal axis.
- Print the deflected shape, superimposed on the undeflected shape.
- Neatly show your hand calculations to check the equilibrium conditions.